

# Statistik Test Vorber.

Test SS 07 12.10.07

$$1) H = \sum_{i=1}^{3N} \left( \frac{p_i^2}{2m} + \frac{1}{2} m \omega^2 q_i^2 \right) = \sum_i^N \hat{p}^2 + \hat{q}^2$$

$$\Omega = \frac{d\phi}{dE} \cdot \Delta E$$

$$\phi = \int d^{3N} q d^{3N} p = \left| \begin{array}{l} \hat{p} = \frac{p}{\sqrt{2m}} \\ \hat{q} = q \sqrt{\frac{m\omega^2}{2}} \\ d p = d \hat{p} \sqrt{2m} \\ d q = d \hat{q} \sqrt{\frac{2}{m\omega^2}} \end{array} \right.$$

$$\begin{aligned} \rightarrow \phi &= (\sqrt{2m})^{3N} \left( \sqrt{\frac{2}{m\omega^2}} \right)^{3N} \int d^{3N} \hat{q} d^{3N} \hat{p} \\ &= \left( \frac{2}{\omega} \right)^{3N} \cdot V_{\text{Kugel}} \\ &= \left( \frac{2}{\omega} \right)^{3N} \frac{(\sqrt{2\pi} E)^{3N}}{2^{3N} (3N)!} \checkmark \end{aligned}$$

$$R = \sqrt{E}$$

$$\Omega = \frac{1}{h^{3N} N!} \frac{d\phi}{dE} \Delta E = \frac{1}{h^{3N} N!} \frac{1 \cdot 3N \cdot E^{3N-1}}{\omega^{3N} 3N!} \cdot \Delta$$

$$= \frac{1}{h^{3N} N! \omega^{3N}} \frac{E^{3N-1}}{(3N-1)!} \cdot \Delta$$

$$b) C_V = \left( \frac{\partial E}{\partial T} \right)_{V, N}$$

$$S = k_B \ln \Omega$$

$$\frac{\partial E}{\partial S} = T \quad \text{eq.} \quad \frac{\partial S}{\partial E} = \frac{1}{T}$$

$$S = k_B \ln \left( \frac{\Delta}{C} E^{3N-1} \right) = k_B \left( \ln \frac{\Delta}{C} + \ln E^{3N-1} \right)$$

$$\frac{\partial S}{\partial E} = \frac{\partial}{\partial E} k_B (\ln E^{3N} - \ln E) = \frac{\partial}{\partial E} k_B (3N-1) \ln E$$

$$\Rightarrow \frac{1}{T} = \frac{k_B (3N-1)}{E}$$

$$E = (3N-1) k_B T$$

$$\frac{\partial E}{\partial T} = (3N-1) k_B = C_V$$

Test 14.5.07

$$S(E, V) = A E^{\frac{1}{2}} + B V^{\frac{2}{3}}$$

S	E	V
U	F	
P	G	T

a) Berechne P & E(V, T)

$$dE = T dS - P dV$$

$$\rightarrow dS = \frac{dE}{T} + \frac{P}{T} dV$$

$$dS = \frac{\partial S}{\partial E} dE + \frac{\partial S}{\partial V} dV = \frac{A}{2 E^{\frac{1}{2}}} dE + \frac{B}{2 V^{\frac{1}{3}}} dV$$

$$\Rightarrow \frac{1}{T} = \frac{A}{2 E^{\frac{1}{2}}} \quad \& \quad \frac{P}{T} = \frac{B}{2 V^{\frac{1}{3}}}$$

$$\left(\frac{A T}{2}\right)^2 = E$$

$$P = \frac{B T}{2 V^{\frac{1}{3}}}$$

b) i  $dE = \delta Q + \delta W$   
 $\Rightarrow dQ = dE + p dV$

$P_1 \rightarrow P_2, V_1 \rightarrow V_2$

$$Q = \int_{P_1}^{P_2} dQ + \int_{V_1}^{V_2} dQ$$

hier  $dV=0$  hier  $dp = p$

$$E = \frac{A^2 T^2}{4}$$

$$P = \frac{B T}{2 \sqrt{V}} \rightarrow T = \frac{P \sqrt{V} 2}{B}$$

$$\Rightarrow E = \frac{A^2 P^2 V 4}{4 B^2}$$

$$dE = \frac{A^2}{B^2} (2 P V dp + P^2 dV)$$

$$\rightarrow Q = \frac{A^2}{B^2} \int_{P_1}^{P_2} 2 P V dp + \int_{V_1}^{V_2} \frac{A^2}{B^2} P^2 + P dV$$

$$= \frac{A^2}{B^2} V_1 (P_2^2 - P_1^2) + \left(\frac{A^2}{B^2} P_2^2 + P_2\right) (V_2 - V_1)$$

$$C = \frac{\partial Q}{\partial T}$$

$$\begin{aligned} dQ &= dE - dW \\ &= dE + p dV \end{aligned}$$

$$C_v = \left( \frac{\partial E}{\partial T} \right)_V \quad // \quad E = \frac{A^2 T^2}{4}$$

$$\Rightarrow C_v = \frac{A^2 T}{2}$$

$$V = \frac{B^2 T^2}{p^2 x^2}$$

$$\begin{aligned} C_p &= \left( \frac{\partial Q}{\partial T} \right)_p = \frac{\partial E}{\partial T} + p \frac{\partial V}{\partial T} = \frac{A^2 T}{2} + p \frac{B^2 2T}{p^2 x^2} \\ &= \frac{A^2 T}{2} + \frac{B^2 T}{2} \end{aligned}$$

$$\text{ii) } (p_1, V_1) \rightarrow (p_2, V_2)$$

$$x = \frac{p}{V}$$

$$dV = \frac{dp}{x}$$

$$V = \frac{p}{x}$$

$$dQ = \frac{A^2}{B^2} (2pV dp + p^2 dV)$$

$$+ p dV = \frac{A^2}{B^2} \left( \frac{2p^2}{x} dp + \frac{p^2}{x} dp \right)$$

$$+ \frac{p}{x} dp = \frac{A^2}{B^2} \left( \frac{3p^2}{x} dp \right)$$

$$+ \frac{p}{x} dp$$

$$Q = \int_{p_1}^{p_2} \frac{A^2 3}{B^2 x} p^2 dp + \frac{p}{x} dp$$

$$= \frac{A^2}{B^2 x} (p_2^3 - p_1^3) + \frac{(p_2^2 - p_1^2)}{2x} \quad \checkmark$$

$$x = pV$$

$$x = p_1 V_1$$

$$\langle A \rangle = \langle \alpha | A | \alpha \rangle$$

$$\langle \uparrow | S_x | \uparrow \rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}^\dagger \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} =$$

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$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ (1 \ 0) \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} \underline{\underline{0}}$$